INSTALLATION & ALIGNMENT OF HS-3/R ATC 38, SIDEMOUNT TOOL CHANGER

HS-3/R AUTOMATIC TOOL CHANGER SPECIFICATIONS

Tool Storage Capacity	38			
Maximum Tool Length (referenced from gage line)	600 mm (23.6 in)			
Maximum Tool Diameter	250 mm (9.8 in)			
Maximum Tool Diameter with Adjacent Tool Pockets Filled	125 mm (4.9 in)			
Maximum Tool Weight	36 kg (79.4 lb)			
Maximum Tool Moment (referenced from gage line)	300 kg-cm (260 lbf-in)			
Tool Pot Chain Pitch	130 mm (5.12 in)			
Tool Taper	CAT50			
Pull Stud Type	MAS P50T 45º			
Hydraulic Pressure	50 kgf/cm2 (711 lbf/in2)			
Hydraulic Flow-rate	30 l/min (8 gal/min)			

INITIAL SET-UP PROCEDURE

THIS SECTION ASSUMES THE MORI TOOL CHANGER ANCHORS HAVE BEEN INSTALLED IN THE SHOP FLOOR AND THAT THE HORIZONTAL MILL HAS BEEN PROPERLY LEVELED AND ANCHORED. DO NOT ATTACH THE MORI TOOL CHANGER TO THE BASE OF THE MILLING MACHINE PRIOR TO LEVELING THE MACHINE. IF NECESSARY REFER TO THE HS-3/R OPERATORS MANUAL FOR INSTRUCTIONS ON HOW TO INSTALL THE TOOL CHANGER ANCHORS.

1. Temporarily block the tool changer up on its base plate and install the six leveling blocks on the bottom of the base plate, Figure 1.

2. Verify that the four main leveling screws (the large hollow screws located at all four corners) and the four intermediate leveling screws (the hex head bolts located on each of the four sides of the base plate) are adjusted so that they are flush with the bottom of the tool changer's base plate, Figure 1.

3. Lift the tool changer with the arm mechanism facing towards the front of the HS-3/R. Move the tool changer over the top of the pre-installed anchor bolts and lower it such that the hollow leveling screws slide over the anchor bolts.

4. An alignment bracket is used to provide the initial "rough" alignment of the tool changer to the horizontal mill. Attach the alignment bracket to the base of the tool changer using three M16 X 60mm metric socket head cap screws (Haas P/N 40-0039), Figure 2. **Install, but do not tighten the screws at this time.** In addition, it may be necessary to move the tool changer's base plate a small amount to bring the alignment bracket into its proper position.

5. Place a bubble level on the tool changer's base and using the four main leveling screws (the large 60mm hex screws located in the corners of the base plate) bring the tool changer base plate into level. During this leveling procedure, verify that the height of the slots on the vertical face of the alignment bracket are at the same elevation as the threaded holes in the pad located on the side of the milling machine's base, Figure 2. If necessary, re-adjust the leveling screws to bring the alignment bracket to the proper elevation.

6. When the tool changer is level and the four slotted holes in the alignment bracket are lined up with the threaded holes in the pad, attach the alignment bracket to the base of the mill using four $3/8-16 \times 11/4$ socket head cap screws. Finish attaching the bracket by tightening the three M16 cap screws.

7. Next, thread the four intermediate leveling bolts (the four bolts with 30mm hex heads located near the center of each side of the base plate) down until they just touch the leveling blocks. Further tighten the bolts approximately another 1/8 turn past this point to insure these screws are each sharing some portions of the load.

8. Complete the base plate installation by installing the nuts and washers onto the threaded ends of the tool changer anchor bolts and tightening to 230 ft-lb. Note that these are metric threads and nuts.

9. Remove the two yellow shipping brackets located on the tool changer's arm assembly, Figure 3.

10. Install the tool changer guard around the tool changer and make the following electrical connections:

a) Connect the remote control box cable to the tool changer junction box.

b) Route and connect the cables from the tool changer junction box to the connectors located on the side of the machine's control box.

INSTALLING THE HYDRAULIC POWER UNIT

HYDRAULIC POWER UNIT SPECIFICATIONS

MAXIMUM PRESSURE	1000 PSI
MAXIMUM FLOWRATE @ 1800 RPM	10.5 GPM
RESERVOIR VOLUME	20 GAL.
PRESSURE HOSE (Haas P/N 52-0008)	1/2 JICF X 1/2 JICF X 84" L
RETURN HOSE (Haas P/N 52-0000)	1/2 JICF X 1/2 JICF X 90" L

INITIAL SET-UP OF HYDRAULIC POWER UNIT

1. Check the level of the hydraulic fluid in the reservoir by inspecting the sight gage located on the side of the reservoir. If necessary, add hydraulic fluid (DTE 25) to the reservoir until the level reaches the top of the sight gage.

2. Connect the pressure and return hoses from the hydraulic power unit (HPU) to the tool changer. The pressure hose connects the pump outlet to the middle port on the tool changer manifold; the return hose connects the bottom port on the tool changer manifold to the filter inlet on the hydraulic power unit, Figure 4. NOTE: IF THE HPU IS TO BE OPERATED FOR THE FIRST TIME, SKIP TO STEP 7 FOR INITIAL ADJUSTMENT OF THE HYDRAULIC SYSTEM'S PRESSURE AND FLOW SETTINGS.

3. Connect the supply air-line (1/4" plastic hose) from the machine's air-lube panel to the upper fitting on the tool changer manifold.

4. Connect the power cord from the hydraulic power unit's motor to the power connection located on the side of the milling machine's control box.

5. Check the rotation direction of the hydraulic power unit's motor using the following procedure:

a) Remove the orange inspection from the bell housing located between the motor and the hydraulic pump, Figure 5.

b) Power-up the HS-3/R but **DO NOT CLEAR THE ALARMS UNTIL THE NEXT STEP**.

c) With an observer watching the coupling inside the inspection window, push the <**RESET**> button on the keypad and immediately push the <**E-STOP**> button. This will jog the motor on the hydraulic power unit.

d) Note the rotational direction of the power unit's motor and compare with the directional arrow located on the front of the hydraulic pump's casing.

e) If the rotation matches the rotation of the directional arrow the machine is correctly wired. If the rotation does not match then the phasing of the machine's power must be changed by reversing any two of the incoming three wires of the machine's power wiring.

f) If it was necessary to re-wire the machine, re-check and verify that the motor is rotating in the correct direction.

6. When it has been verified that the motor is rotating in the correct direction, turn the hydraulic power unit on by powering-up the machine and clearing the alarms. **NOTE: THE HYDRAULIC POWER UNIT OPERATES ANY TIME THE MACHINE IS POWERED-UP AND THE ALARMS ARE CLEARED.**

7. When the pump is to be operated for the first time, the discharge side of the pump should be in a no-load state. This is accomplished by connecting the pump's discharge (pressure) hose directly to the inlet of the return filter connection.

The motor should be started and stopped 5 to 6 times to bleed any air from inside the pump. After verifying that the pump is discharging oil by feeling the discharge hose or cracking one of the hose's fittings, the pump should be operated for at least 10 minutes without any load to remove any remaining air in the circuit.

8. To adjust the hydraulic system's flowrate perform the following steps:

a) The flowrate is adjusted with the hydraulic power unit operating in a no-load

state.

b) Install a hydraulic service flowmeter rated for 1 to 15 gpm in-line with the hose connecting the pump discharge to the filter inlet of the hydraulic power unit, Figure 6.

c) Power-up the hydraulic power unit and adjust the pump's discharge flowrate by turning the flow adjustment screw (the horizontally oriented screw with lock-nut), Figure 7, clockwise to decrease the flowrate and counter-clockwise to increase the flowrate. The correct flowrate for operation of the ATC 38 tool changer is 8 gpm. Note that it may be necessary to first adjust the pump's "open system" discharge pressure to achieve 8 gpm. This is done by adjusting the vertically oriented screw. Approximately 300 to 375 psi will be the maximum achievable pressure when in the "open system" operating mode.

9. After the flowrate has been adjusted, reconnect the hydraulic hoses as described in Step 2.

10. Power-up the machine and check the pressure gage on the HPU to verify that the system pressure is in the range of 700 to 750 psi. This is the "blocked system" pressure.

If necessary this pressure can be adjusted by turning the pressure adjusting screw (the vertically oriented screw with lock-nut), Figure 7, on the pump in a clockwise direction to increase pressure and counter-clockwise to decrease pressure.

11. The tool changer is now fully connected and ready for alignment.

NOTE: FINAL ALIGNMENT OF THE TOOL CHANGER TO THE MACHINE'S SPINDLE MUST BE PERFORMED BEFORE THE TOOL CHANGER CAN BE USED TO CHANGE TOOLS.

TOOL CHANGER OPERATION

The ATC 38 tool changer is a hydraulically powered unit that operates in a sequential manner. That is, each of four arm functions must fully complete its motion before the next function is allowed to begin. For example, the arm must complete its slide-left function before the arm is allowed to perform its push-out function. In operation the system verifies that the arm or other component has made it to its desired final position before it will allow the next function to begin.

Table 1., SEQUENCE OF ATC OPERATION, provides a step-by-step "snap-shot" of eachsequence of the tool changer's automatic operation beginning with the tool changer in its HOMEposition. This automatic sequence must also be used for manual operation of the tool changer.

OVERVIEW: TOOL CHANGER RECOVERY

The tool changer recovery mode is used to manually move the tool changer's arm and carriage into either its HOME position (describe below) or into its alignment position. The tool changer has a total of 13 separate functions that can be operated from the control panel or the remote control box located on the tool changer's cage guard. The tool changer recovery mode (accessed through the use of the **<TOOL CHANGE RESTORE**> button on the keypad) provides direct access to 10 of the tool changer's functions. There are 8 functions that can be controlled from the first tool changer recovery screen. These are listed on the **TOOL CHANGER RECOVERY** screen and are controlled by using the cursor buttons. These functions are:



TABLE 1. SEQUENCE OF ATC OPERATION

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TABLE 2 MANUAL TOOL CHANGER OPERATION FROM THE CONTROL PANEL					
FUNCTION NO.	BUTTON NAME/CONTRO	L KEY	OPERATION		
1	HOME BUTTON <ho< td=""><td>ME></td><td>SWING ARM TOWARDS SPINDLE</td></ho<>	ME>	SWING ARM TOWARDS SPINDLE		
2	PAGE DOWN <page do<="" td=""><td>WN></td><td>SWING ARM TOWARDS MAGAZINE</td></page>	WN>	SWING ARM TOWARDS MAGAZINE		
3	UP ARROW	<^>	PULL ARM IN		
4	DOWN ARROW	<v></v>	PUSH ARM OUT		
5	END BUTTON <e< td=""><td>ND></td><td>ROTATE ARM COUNTER-CLOCKWISE *</td></e<>	ND>	ROTATE ARM COUNTER-CLOCKWISE *		
6	PAGE UP BUTTON < PAGE	UP>	ROTATE ARM CLOCKWISE *		
7	LEFT ARROW	< < >	SLIDE ARM TO LEFT *		
8	RIGHT ARROW	< > >	SLIDE ARM TO RIGHT *		

*: As viewed from the magazine side of the tool changer.

In addition, as the tool changer recovery screens are paged through, the tool changer door can be opened and closed (functions 9 and 10). When required the tool changer recovery sequence will state that the door must be opened or closed using the "O" or "C" buttons on the alpha keypad.

TABLE 3 MANUAL TOOL CHANGER OPERATION FROM THE CONTROL PANEL							
FUNCTION CONTROL KEY OPERATION NO.							
9	<0>	OPENS TOOL CHANGER DOOR					
10	<c></c>	CLOSES TOOL CHANGER DOOR					

The final three functions are accessed from the remote control box located on the tool changer's cage guard:

TABLE 4 MANUAL TOOL CHANGER OPERATION REMOTE CONTROL PANEL, TOOL CHANGER CAGE GUARD							
FUNCTION NO. CONTROL ELEMENT OPERATION							
11	FOOT SWITCH	PUSHES TOOL OUT OF TOOL POCKET					
12	ROTATE CCW BUTTON	ROTATES THE MAGAZINE COUNTER- CLOCKWISE					
13	ROTATE CW BUTTON	ROTATES THE MAGAZINE CLOCKWISE					

TOOL CHANGER ALIGNMENT PROCEDURE

1. To begin the alignment procedure of the tool changer perform the following steps:

a) Press **<POWER ON>** button.

b) Go to the **PARAMETERS** screen and set **Parameters #211** (Y-axis) and **#64** (Z-axis) to zero.

- c) Press <**ZERO RETURN>** and **<AUTO ALL AXIS>** buttons.
- d) Press <**MDI**> button then press <**ORIENT SPINDLE**> button.
- e) Press <TOOL CHANGER RESTORE> button.

At this point the machine will ask the operator to verify the locations of any tools and the status of the tool changer door. When the conditions asked for on the screen are met press **<Y>**, this will simultaneously open the tool changer door and to move the next screen.

This screen gives a warning that tools may fall during the following process. The operator is asked to press $< \mathbf{Y} >$ to continue the process.

The new screen states:

PRESS A TO ATTEMPT AUTO RECOVERY

PRESS M TO GO TO MANUAL RECOVERY

Press **<M>** to go into manual recovery mode.

The next screen states:

A= Arm

M= Magazine

O= Open Door

C= Close Door

Press <M> on the keypad to home the tool changer magazine. After the magazine has reached its home position press <A> to go to the control screen for the tool changer's arm functions.

The next screen states:

Hydraulic tool changer bump arm

Using arrow keys attempt to move the arm into its home position

Pressing the cursor keys described in Table 2 will move the tool changer's arm and carriage.

NOTE: THE TOOL CHANGER'S ARM AND CARRIAGE ASSEMBLY WILL "JERK" AND "SHAKE" WHEN IT IS OPERATED MANUALLY BY USING THE CONTROL PANEL KEYS. BECAUSE THE MOTION IS SOMEWHAT ERRATIC, THE SAFETY OF PERSONNEL AND EQUIPMENT SHOULD BE TAKEN INTO CONSIDERATION WHEN OPERATING IN THIS MODE.

!!!SAFETY WARNING!!!

WHEN OPERATED IN THE MANUAL MODE IT IS POSSIBLE TO MOVE THE TOOL CHANGER'S ARM AND CARRIAGE INTO A POSITION THAT MAY DAMAGE THE TOOL CHANGER AND/OR THE HORIZONTAL MILL. BEFORE MANUALLY OPERATING THE TOOL CHANGER THE MACHINE OPERATOR MUST FULLY UNDERSTAND THE MOTION OF THE TOOL CHANGER'S ARM AND CARRIAGE DURING A NORMAL TOOL CHANGE CYCLE.

MOST IMPORTANTLY DO NOT ATTEMPT TO SWING THE TOOL CHANGER ARM TOWARDS THE SPINDLE UNLESS THE PHRASE "ARM HOME" IS DISPLAYED ON THE TC RECOVER SCREEN.

2. The next step in the alignment procedure is to move the tool changer's arm to its **HOME** position by using the cursor buttons described in Table 2. <u>The **HOME** position is defined as</u>:

a) The arm is **<u>fully rotated</u>** towards the magazine, using the **<PAGE DOWN >** button.

b) The arm is <u>fully pulled in</u>, using the $<^{\Lambda}>$ up arrow button.

c) The arm is rotated <u>fully clockwise</u> or <u>fully counter-clockwise</u>, using the **<END>** button or the **<PAGE UP>** button until the arm is in a horizontal position.

d) The arm is moved <u>fully to the right</u>, using the <>> right arrow button.

When the tool changer arm has been moved into its **HOME** position the control panel screen will display a highlighted line that states **ARM HOME**. Prior to reaching the **HOME** position the display screen will be blank in this area. As a check, when the arm is in the **HOME** position, the cam follower located on the bottom of the slide mechanism will be in-line with the cam slot on the guide plate.

By using the cursor keys and the messages displayed on the **TOOL RECOVERY** screen, move the tool changer's arm into its **HOME** position. The tool changer's arm and carriage must be moved to their <u>full limit</u> of travel to achieve the **HOME** position. Even when it appears that the full limit of travel has been reached, push the button several more times to ensure that, in fact, the full limit of travel has been reached.

3. A three-piece alignment tool is available as an aid for aligning the tool changer's arm to the machine's spindle, Figure 8. Using the **<TOOL RELEASE**> button install the taper section of the alignment tool, Figure 9, into the machine's spindle. Next, insert the flanged end of the alignment tool, Figure 10, into the gripper claws of the arm.

4. Before performing this step, verify that the spindle and column are at their zero limits of Y and Ztravel.

Press the **<HOME>** button to swing the tool changer arm into the machine enclosure. After the arm has rotated fully into the enclosure push the **<>>** (right arrow) button to slide the arm towards the center of the machine.

With the arm in this position, place a level on its top edge and verify that the arm is level. If it is not level re-adjust the leveling bolts on the base of the tool changer to bring the arm into level.

5. Handle-jog the spindle to bring the centerline of the bore of the tapered section of the alignment tool into rough alignment with the centerline of the bore of the flanged section of the alignment tool in the gripper claws. Move the column in the Z-axis direction to create a 0.005" gap between the faces of the two halves of the alignment tool. If the two faces are not parallel, use the leveling screws on the base of the tool changer to bring the faces into a parallel condition.

6. To perform the final portion of the alignment procedure it is necessary to loosen the six clamp bolts that join the tool changer to its base plate and use the adjusting bolts located on the sides of the base plate to move the tool changer in the +/- X-axis direction. Using the +/- X-axis direction adjusting bolts and the Y-axis handle jog move the tool changer and the spindle to align the bores in the two halves of the alignment tool such that the alignment dowel can slide through both bores, Figure 11. Note that the alignment dowel has a small and a large diameter section. This is to enable a "course adjustment" and then a "fine adjustment" to be made.

7. Tighten the six clamp bolts on the tool changer base and verify that the alignment dowel still slides through the bores in the alignment tool halves.

SETTING THE TOOL CHANGE POSITION PARAMETERS

8. Without moving the tool changer arm, spindle or column from the position achieved in Step 7, do the following:

a) Go to the SETTINGS/GRAPH display screen by pressing the <SETNG/GRAPH> button.

b) Go to Setting **#7**, **PARAMETER LOCK** and change it to **OFF** by pressing <>> (right arrow) button and then press the <**WRITE/ENTER**> button to save it in memory.

c) Go to the **ALARMS** display screen by pressing the **<ALARM/MESGS>** button. Type in **DEBUG** from the keypad and press the **<WRITE/ENTER>** button.

d) Move to the **POSITION** display screen by pressing the **<POSIT>** button. Press the **<PAGE UP>** button to move to the **POS-RAW DAT** screen.

e) Record the values shown in the **ACTUAL** column for the position of the Y and Z-axes.

f) Go back to the **ALARMS** screen, type in **DEBUG** and press the **<WRITE/ENTER>** button to exit the **DEBUG** mode.

g) Press the **<E-STOP>** button to allow parameters to be changed.

h) Go to the **PARAMETERS** display screen by pressing the **<PARAM/DGNOS>** button. Go to Parameter **#211**, **Y** Tool Change Offset, on the "**Y** PARAM B" screen. Enter the number (with the correct sign) recorded from the **POS-RAW DAT** screen for the Y-axis and press the **WRITE/ENTER** button.

NOTE: THESE PARAMETER NUMBERS ARE ENTERED WITHOUT A DECIMAL POINT AND MUST BE THE SAME SIGN AS THAT GIVEN ON THE POS-RAW DAT SCREEN. FOR EXAMPLE -0.7094 WOULD BE ENTERED AS -7094 AND -278.8854 WOULD BE ENTERED AS -2788854.

i) Go to Parameter **#64, Z Tool Change Offset,** on the "**Z PARAM B**" screen. Enter the number (with the correct sign) recorded from the **POS-RAW DAT** screen for the Z-axis and press the **WRITE/ENTER** button.

NOTE: ENTERING A VALUE OTHER THAN ZERO FOR PARAMETER #64 CREATES A NEW "ZERO" POSITION FOR THE MACHINE'S Z-AXIS WHICH IS FORWARD OF THE ZERO LIMIT FOR THE MACHINE. THUS, WHEN PROGRAMMING THE POSITION OF THE Z-AXIS IT IS POSSIBLE TO USE BOTH POSITIVE AND NEGATIVE VALUES FOR THE Z-AXIS POSITION.

j) Because of the new "ZERO" position for the machine the value for Parameter #34, Z – axis Maximum Travel must be adjusted to reflect the new "ZERO" position. To calculate the new value use the following formula: (Parameter #33) x (Z –axis travel distance) – (Parameter #64) = (Parameter #34), where:

(Parameter #33) is Z-axis encoder steps per unit (unit = 1 inch)

(Z-axis travel distance) is the machine's total Z-axis travel in inches (60 in.)

(Parameter #64) is the Z Tool Change Offset value in encoder steps

(Parameter #34) is the Z-axis Maximum Travel in encoder steps

Example: $(138718 \text{ steps/inch}) \times (60 \text{ inches}) - (1052517 \text{ steps}) = 7270563 \text{ steps}$ Go to the "**Z PARAM B**" screen and enter this number for **Parameter #34**.

k) Remove the **E-STOP** condition by pulling out the **<E-STOP**> button and press the **<RESET**> button twice to return to normal machine operation.

I) Push the <**TOOL CHANGE RESTORE**> button and gain access to manual control of the tool changer.

m) Using the tool change recovery cursor buttons, move the tool changer carriage out of the machine enclosure to its home position and remove the alignment tool from the spindle and the tool changer arm.

n) Complete the Tool Change Restore operation to close the tool changer door.

o) POWER OFF and then POWER ON the machine. Press the <RESET> button twice to clear any alarm messages and then verify that parameters #211, #64 and #34 retain the correct offset values.

p) Push the **<ATC FWD**> button and visually verify that the tool changer is functioning properly and that the tool changer arm correctly positions itself for a tool change.

q) Install a tool in the spindle and perform a live tool change. Inspect the entire sequence of operations for the tool changer and verify that the tool changes are being made in a smooth and safe manner.

ADJUSTING THE OPERATING SPEED OF THE ATC 38 HYDRAULIC TOOL CHANGER

The speed of the various functions on the ATC 38 tool changer can be adjusted. In general, the goal of adjusting the tool changer speed is to achieve a high operational speed (or low tool-to-tool change time) that does not cause undo deflection or vibration of the tool changer. In addition, consistency of motion must also be considered, that is, it is best to equalize the speed of reciprocal functions (rotate clockwise and counter-clockwise, slide left and slide right, etc.) to produce a consistent flow of motion as the tool changer operates.

NOTE: IT IS POSSIBLE TO CAUSE DAMAGE TO THE TOOL CHANGER IF THE SPEEDS ARE TOO HIGH. APPROACH THE ADJUSTMENT OF THE TOOL CHANGER'S SPEED WITH CAUTION.

1. The speed of the following nine functions on the ATC 38 tool changer can be adjusted:

- I) Carousel speed
- II) Carriage swing speed, toward carousel
- III) Carriage swing speed, toward spindle
- IV) Carriage slide speed, left direction
- V) Carriage slide speed, right direction

VI) Arm speed, push-out

VII) Arm speed, pull-in

VIII) Arm rotation speed, clockwise

IX) Arm rotation speed, counter-clockwise

The Carousel speed and the Arm's pull-in/push-out speed are directly controlled by the flowrate of the hydraulic pump. Thus, increasing the flowrate will increase the speed of these functions and conversely decreasing the flowrate will decrease their speed. The speed of the other six functions are controlled by flow control valves located on the tool changer's valve manifold, Figure 12.

2. If it is necessary to adjust the speed of a function controlled by a valve perform the following:

a) Locate the valve that controls the function.

b) Loosen the lock-nut on the appropriate flow control valve.

c) Turn the flow control adjustment screw counter-clockwise to increase flow (increase speed), or turn the adjusting screw clockwise to decrease flow (speed). NOTE: MAKE ADJUSTMENTS IN 1/4 TURN INCREMENTS AS SMALL ADJUSTMENTS CAN CAUSE LARGE CHANGES IN SPEED.

d) After completing the adjustment, tighten the adjustment screw lock-nut.





Figure 2a



Figure 2b



Figure 4



Figure 7



Figure 10



Maintenance Manual Of ATC 38/50#

For Haas Automation, Inc

Mori Machinery Corporation

Okayama-Japan

MORI MACHINERY CORPORATION

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Attached Drawings

1. ATC assembly 38	1 M 2098A			
1. Magazine assembly 38	1M2163A			
① Main drive assembly	1M2016A			
② Tension assembly 38	2M0248A			
③ Tool release assembly 38	2M0425A			
④ Base assembly 38	1M2017A			
(5) Cover assembly 38	1M2025A			
2. Changer assembly	1M2164A			
① Arm assembly	1M2097A2			
3. Valve assembly	1M2102A			

Spare parts list

Outline of the machine 1

This machine is "ATC equipment" made for the purpose of changing spindle tools automatically.

This machine consists of magazine unit of which maximum capacity of tools are 38 tools (Tool dia. under 125mm) and ATC changer unit, and is actuated by hydraulic system.

ATC magazine is Link chain system and contributes to shortening time for indexing tools by adopting clockwise and counterclockwise indexing function.

ATC arm is double arm type and contributes to the short tool change time as it grips the next tool from ATC magazine while machining.

Specification 2

2-1 Specification of tools

- Tool storage capacity : 38 Tools
- Tool shank : CAT50#
- Pull stud : MAS P50T-1 (45)
- Max. Tool diameter : 125 mm (with adjacent tools)
- : 250 mm (without adjacent tools) Max. Tool length : 600 mm : 36.0 kg 8265 300 - Max. Tool weight : 15.0 kg (Average tool weight)

: 300 kg cm

60 Tou

2its a irhadjacuit

2-2 Specification of machine

Max. Tool moment

- : 38 tools (On condition tool dia. is under 125 mm) Max. Tool capacity
- Tool pot chain pitch : 130 mm
- Tool selection : Clockwise and counterclockwise is possible. Drive system : ATC changer unit : Hydraulic (77 kg/cm2): Magazine : Hydraulic (77 kg/cm2)
 - : Tool pusher (Manual) : Air
- (4kg/cm2)

15 by max for cylecole:



3 Details of ATC

3-1 Magazine

Hollow-pin type tool pot chain makes rotation by hydraulic motor (index motor) equipped with positioning function. Reduction gear ratio is 1/12 when using drive sprocket (T12). (Motor shaft 1 rotation / 1 pot)

As this tool pot's pitch is 130mm and guarded by polymeric resin, under no dispensing oil condition, smooth movement is possible.

3-2 Manual tool change of magazine

Pushing the pull stud from magazine side of the tool pot by air-cylinder does the function of tool pullout from the tool pot. Pull out the tool supporting with your hands on the tool, as the tool is pushed out with the movement of air-cylinder actuated by footswitch. Also the tool should be inserted into the tool pot confirming the direction of the tool key.

3-3 ATC changer unit

Hydraulic unit drives ATC changer unit. As the movement of ATC changer unit is on the linear guide, smooth movement is possible. The movement is actuated by hydraulic motor and rack and pinion. At the end of the linear guide, this unit has shock absorbers which function not only shock absorbing but also as a mechanical stopper.

Arm rotation is 180-degrees with rack movement by hydraulic cylinder. IN/OUT of arm is also actuated by hydraulic cylinder, and each cylinder's type is stated on the Electric parts list. Stroke adjustment except arm-out end position is possible by outside mechanical-stopper. This mechanical-stopper is indicated on **DWG 1**. Please refer to the **DWG 1** while the alignment work is being done.

• Caution:

The 180-degree rotation cannot be done while arm is IN due to the interference between dogs for mechanical-lock cancellation and arm. The 180-degree rotation should be done under the condition of arm-OUT when changer is at the tool changing location with spindle. Furthermore keep the following conditions.

Changer 90-degree rotation is made from:

MG side to spindle side: Changer must be at the right traverse end. Spindle side to MG side: Changer must be at the left traverse end.



3-4 ATC Arm

The grippers of the arm have both mechanical lock function and hydraulic Lock function. Mechanical lock function is cancelled if the lock pin at the reverse side of the arm is pushed. As hydraulic lock is using hydraulic of arm-OUT, the lock functions at a time of movement of arm-OUT and is cancelled at a time of movement of arm-IN.

Refer to agenda "4-2", when needed, which explains the clearance and the way of adjustment between the arm and the dog for mechanical-lock cancellation.

• Caution:

As explained above, hydraulic lock is cancelled only at the movement of arm-IN.

In case solenoid valve is at the neutral position, hydraulic lock cannot be cancelled.

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4 Alignment

4-1 Alignment work of ATC arm and Spindle

Alignment work of ATC arm and Spindle should be done as follows.

: Y, Z-axis direction is done at the spindle side.

: X-axis direction is with the movement of ATC magazine.

Parallel adjustment of X-Y axis plane and ATC arm (parallel between spindle nose and arm) should be done at ATC side. Alignment allowance and its way of alignment are indicated on **Chart 1.**

	Allowance	Way			
X direction	± 0.1	ATC body movement			
Y direction	± 0.1	Spindle Y-axis			
Z direction	2 ± 0 . 1	Spindle Z-axis			

Chart 1. Alignment allowance and its way





Movement of ATC body is done by jack bolt for adjustment of magazine up down and right-left indicated on **DWG 3.** Alignment of pot and arm has already been adjusted when the machine is delivered to HAAS AUTOMATION Inc, no need to re-alignment.

MORI MACHINERY CORPORATION



4-2 Adjustment of dog for cancellation of arm mechanical-lock.

The clearance between dog for arm-mechanical-lock and arm is indicated on **DWG 4.** The dog adjustment has already been done when the machine is delivered to HAAS AUTOMATION Inc.

But in case you adjusted stopper-bolt for the adjustment of arm-IN end (Re-alignment of clearance between magazine gauge line and arm), re-alignment shall be necessary.

In case clearance is small, you need to grind the reverse side of dog and in case clearance is large, insert the shim beneath the dog.





5 Speed adjustment

Magazine drive, ATC arm-IN/OUT and tool pushing cylinder are oil-flow fixed type actuators and their speeds cannot be adjusted. Other movements' speeds are adjustable as there are flow control valves in the hydraulic circuit. Refer to the valve assembly (attached DWG 1M2102A).

Cylinder cushions of changer 90 and 180-degree rotation are possible to be adjusted from outside.

Slide < 90° Rotate 1.0 sec. 1.4 sec.

- 6 Maintenance
 - 6-1 Check

(1) Magazine

- No unusual sound shall be heard from the magazine drive.
- No dust or cutting chips in the tool pot.
- No cutting chip and other contamination at the tool pot guide area.
- (2) ATC arm
- Smooth movement of arm mechanical-lock pin Struys in griffer block
 Smooth movement of arm
- Smooth movement of arm grippers
- Grippers of the arm do not have any damage

(3) ATC changer unit

- No noise while sliding
- Smooth movement of arm180 degree rotation
- Smooth movement of arm in/out
- Smooth movement of changer 90 degree rotation

Movement confirmation of each actuator shall be done by lead switch and proximity switch. Keep dust and/or oil away from the switches.

Lead switch, proximity switch, hydraulic cylinder and etc. are listed in "Electric parts list".

6-2 Lubrication

Refer to the following lubrication parts **chart 2** and lubricate the oil to the parts of ATC according to the list. Be sure to confirm that the machine is stopped when you dispense oil.

Please refer to the lubrication parts listed also in the attached drawings.

	Lubrication part	Lubricate way	Quantity	Term
	Magazine drive gear	General grease lubricate	Proper quantity	6 months each
	Arm shaft IN/OUT	Molybdenum grease lubricate	Proper quantity	6 months each
	Tool pot	General grease lubricate	Proper quantity	6 months each
	Rack for changer slide	General grease lubricate	Proper quantity	6 months each
l	_inear guide for changer slide	General grease lubricate	Proper quantity	1 year each

Chart 2. Lubric	ation
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6-3 Tool pot chain tension

Tool pot chain tension should be checked regularly.

Although the tension of tool pot chain is adjusted at the shipment, after long years operation stretch of the chain, noise, trouble of the guide etc may arise and the alignment between arm and tool pot may get out of order.

 Please be careful that too tight tension of the tool pot chain shall cause abnormal wear.

Instruction of chain tension adjustment is as follow. Please refer to the attached drawing no. 2M0248A

Tension is located at lower/left area of the magazine (manual tool change side). Loosen the 4 paces of #8 bolt with hole 12×50 from the front of the magazine. By doing this #7 plate shall be movable. Then loosen the #13 hexagon nut, tighten the #12 hexagon bolt, move the plate, and adjust the tension of the tool pot chain. After the adjustment, please tighten the hexagon nut and 4 paces of bolt with hole. Tensioning will not change the indexed pot location, but please check the alignment between manual tool pushing cylinder and tool pot.

6-4 Parts list

In the attached parts list, following information is provided.

- Name of the parts
- Manufacturer of the parts

Prenames	DWG No	Parts name	Description	Number	Maker	Note
Magazine		Proximity	E2E-X7E1	1	OMRON	
Main drive		Proximity	E2E-X2E1	2	OMRON	
assembly	L5179491	Index	EIS-170-2PC-1MAO-HB	1	NOP	
Tool release		SOL. Operated	VFS1120-1DZ-01-F	1	SMC	
assembly		valve Read	A73HL	1	SMC	
Arm assembly	1M2097A02	Arm		1	MORI	Sub assembly
cocombry	GY08617	Claw ANSI		2	MORI	
	GY08618	Claw ANSI		2	MORI	
		Bush	LFB1412	4	OILES	
Changer		Proximity	E2E-X2E1	5	OMRON	
assembly		SWITCH HYD. Motor	OMM-32-B-C	1	SUMITOMO	
		Shock absorber	W-A2M20N016SD	2	ΤΑΙΥΟ	
		Stopper nut	SN-A2M20	2	ΤΑΙΥΟ	
	0.0000	Cam follower	NATR15XLL		NTN	
	3L00089	Shaft External retaining	15	1 1 2	MORI	
		ring Read switch	AX-115	6	ΤΑΙΥΟ	
		H-Hose	N177-06-750-1005=1005	1 🖏	YOKOHAMA	
		H-Hose	N177-06-695-1005=1005	1) 👘	YOKOHAMA	
		H-Hose	N177-06-685-1005=1005	1 👔	YOKOHAMA	
		H-Hose	N177-06-720-1005=1005	1	YOKOHAMA	
		H-Hose	N177-06-715-1005=1005	1 . Ş	YOKOHAMA	
		H-Hose	N1/7-06-670-1005=1005	1 (2)	YOKOHAMA	
		H-Hose	N1//-06-450-1005=1005		YOKOHAMA	
Valva			1017 - 00 - 020 - 1000 = 1000	1 (A)		
valve		Operated		3 1	TOYOOKI	
assembly		valve			IUTUUNI	
				11 - 11 - 11 - 11 - 11 - 11 - 11 - 11		





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1	0M00147	Magazino Frame			712	1	
2		Bye Screw	24			2	
3		Hez Bolt	20×70			8	
4		Hex Nut	20			8	
5	¥700008	Washer			0.12	8	
6	2102741	Terminel Box			4.5	1	
7		Socket Head Capacraw	8×15			- 4	
8	41049462	Name Plate Stay			0.06	1	
9	1	Socket Head Capacrew	8×15	1		2	
10	4M012451	Name Plate	· · · · ·			1	
11	3M02708	Guide 14			2.9	4	
12		Socket Head Capscrew	8×70			2	
13	l	Socket Heed Capacrew	8×25			10	
14	31402728	Guide Rail 14			0.16	4	
15	i i i i i i i i i i i i i i i i i i i	Flat Head Screw	6×15			52	
16	3M027052	Guide 2			3.5	4	
17		Socket Head Capsorew	12×90			6	
18	3102733	Guide Rail 2			0.11	- 4	
19	414042933	Guide 3			2.2	2	
20	4M04337	Guide Rail 3			0.07	- 4	
21	RY84802	Guide			2.2	2	
22		Socket Head Capacrew	12×35			4	
23	1M2016A	Magazine Assy			100	1	
24	2M0248A	Tanaion Assy			40	1	
25	1M2020A	TPC ASSY			130	1	

WATERIAL

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ITTN KA	D, W, G N	0,	PART NAME &	DESCRIPTION	QUALITY	WBIGHT	G 1	G,	G 3	G,	P G
1	3M02710	i	Corner Roller			22.5	1				
2	4M06083		Shaft			6.2	1				
3			Socket Head Capscrew	12x40			4				
4			Retaining Ring	60			1				
5			Bearing	6212ZZ			1				
6			Bearing	6213ZZ			1				
7	3M04125		Plate			9.25	1				
8	•		Socket Head Capscrew	12×50			4				
9			Spring Washer	12			4				
10			Washer	12			4				
11	4M04262	1	Block			1.35	1				
12			Hex Bolt	16×200 S200			1				
13			Hex Nut	16			3				
14			Washer	16			3				
15			Socket Head Capscrew	12 = 55			2				
16	4M04422		Pin			0.1	1				
17			Spring Pin	8 x 4 0			4				
18											
19		1									
20											

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ITEL IO.	D, W, G N	0,	PART NAME &	DESCRIPTION	QUALITY	WEIGHT	G ₁	G,	G,	G 4	PG
1	4M05747		Plate	[·····	······································	0.24	1	1	Ť	<u> </u>	
2			Socket Head Capscrew	8 x 2 0			2	2			
3			Spring Washer	8			2	2			
4			Washer	8			2	2			\square
5	4M05751		Rod			0.15	1	1			
6			Set Bolt	10 * 25			1	1			
7			Air Cylinder	CDQ2B50-15D-A73HLS		0.4	1	1			
8			Socket Head Capscrew	6×45			4	4			
9			Joint	KQL06-02S			2	2			
10			Joint	KQL06-01S			2	2			
11			Sol.Operated directional valve	VFS1120-1DZ-01-F		0.18	1				
12			Socket Head Capscrew	4x10			2	2			
13			Sirenser	AN103-01			2	2			
14			Nipple	SRN02-010J			1	1			
15			Speed Controller	AS4000-02		0.22	1	1			
16			Joint	KQH06-02S			1	1			
17			Foot Switch	OFL-VG-SM2.K		1.7	1	1			
18			Sol Operated directional value	VFS1120-5DZ-01-F		0.18		1			
19											
20											

<u>A Rc1/8</u> (10) (10) <u>B Rc1/8</u>

<u>IN Rc1/4</u>

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TOOL RELEASE ASSY



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	U, W, G NO,	LUKI NUMP C	DESCRIPTION	MOVPILL	INTIGET	-1	- 1	-1	-4	
1	1101913	Base 38			135	1				
2		Hez Bolt	20×90 S90			4				
3		Hex Nut	20			4				
4	4105111	Jack Bolt			0.8	4				
5	4M05110	Nut			0.8	4				
6	4M01558	Foundation Bolt			1.2	4				
7		Hex Nut	20			4				
8		Spring Washer	20			4		_		-
9	F	Washer	20			10				_
10	4107960	Matting Plate			1	4				
11	4108480	Matting Plate			2	4				
12		Socket Head Capacwew	6165		[16				
13		Hex Bolt	20×120 \$120			3				_
14	Y700008	Washer			0.1	6				_
15		Hex Nut	3-20			6				
18										
17										
18					· · · · ·					
19										
20						<u> </u>			_	_







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ittii i	D, W, G N	0,	PART NAME &	DESCRIPTION	QUALITY	TE IGET	¢,	6 t	61	٩,	PG
1	3003996	1	Cover	_		2.0	1				
2			Botton Head Bolt	8×10			8				
3	4104091	3	Cover			1.2	1				
4	KY69535	1	Cover				1				
5			Botton Head Bolt	8x15			2				
6	RY78112		Cover			-	1			-	_
7			Botton Head Bolt	6 × 1 0			5				
8	31406739		Coter			6.3	1				
θ		-	Washer	8			5				
10			Spring Washer	8			б				
11	4M04510	1	Plate 4			0.38	3				
12			Socket Head Capacrew	12=30			3				
13	4106238		Collar 19			0.04	1				
14	4104309	1	Bolt			0.4	1				
15	4M06239		Collar 28.5			0.06	1				
16	2102454		Oil Pan 38			10.6	1				
17			Socket Head Capacrew	8=20			4				
18			Plug	3/4B			1			_	
19			Hex Nut	12			1				
20			Socket Head Capacrew	12×60			1				
21											
22	1										
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CHANGER

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41	BY01907	6	Under Bracket				1	i			L
42			Secket Head Capacrew	12X40			12				Г
43			Parailel Pin	10X40			5				Г
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48							-				-
48	3004121	1	Hyd, Cylinder				1				L
50		_	Secket Head Capacrew	10X25			4				
51	3L00068	1	Rack				1				
52	L395294	2	End Housing				1				Г
53			Secket Head Conscrew	8X25			16				Г
54	¥200001	-	Stopper Bolt				1				F
55			Hex Nut	3-16			1				F
100	C446089	-	Reab	0 10			î	-			ŀ
50	VVEE 080	T					+				ŀ
150	VI22310	1	Keck	677.4.6			1	_			┝
58		-	Secket Hoad Capterer	6X4U			4	_			⊢
59			Taper Pia	6X30			2				-
60	2L00026	3	Motor Bracket				1				L
61			Hyd, Miotor OMM	32B-B ¥YUKBN			1				
62			Secket Head Capacrew	6X45			3				Г
63			Set Screw	8X15			ĩ				r
64	4102956		Cover				1	_			F
11		H	Pan Band Sever	6710			5	-			F
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	W12121	\vdash	LIAUAT GUIDE	6704			H	 			┝
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68	3100060	1	Gear 12				1				1
69		L.	Hex Sovew	6X35			1				Ĺ
70											ſ
71	3L00073	-	Stopper Piscs				2				Г
1 7 9	1		Set Screw	5 % 5			2				F
1.55	WV68619	1	Shaft				H	\vdash			۲
13	FI03019	1	Derellel Die	14715			÷	_		-	┝
14		_	Parallel Pin	10235			1			_	┝
75			Bush	LFB-2825			1				L
76	3L00076		Cover				2			1	
17			Bearing	33009JR+KOYO			2				Г
78			U' Nut	M45X1.5*FUJI			1				Г
79	RY78120	2	Shaft				ĩ				r
20		-	Bearing	600822			1				F
21		-	Retaining Ring	40			Ť				ŀ
101			Cashad Blue	Dol /0			÷				┝
82		-	Socret Fins	KC1/8			Ŧ				4
83	RY47297	2	Stopper Block				1				L
84		_	Sockot Head Capacrow	10X25			2				L
85			Spring Pin	10X20			2	_			Γ
86	3L00223		Block				2				Г
87		-	Sackes Head Capacrew	10X65			4				F
1 2 2		-	Mini Coffeen Las	MEANAL SCRUTA INA			2				F
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30	3801099	3	Consector				Ļ	_			⊢
31		_	Secket Head Capacrew	8820			4				L
92	RY74200		Block				1				L
93		L.	Hose Joint	1036-04-06			6				ĺ
94			HOSE N117-06-	750 1005-1005			1				٢
85			HOSE N117-06-	6#5 1005-1005			1				٢
1 4 6		⊢	HOSE N117-04-	685 1005-1005			Ť				F
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1 9 9		L	Tube Fitting	KCT10-030B			5				ŀ
100			Tube Fitting	KLN10-030E			1			_	L
101		L	Tube Fitting	KHB10-030E			2				Ľ
102			Tube Fitting	KLA10-000B			2				ſ
103			Steel Tube	10X1.5			1				Γ
104			-				Ĥ				F
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109	4M08955	2	CYL Plate			1.2	1				L
110		L	HOSE N117-05-	715 1005=1005			1				Ľ
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	D, W, G M	р,	PART NAME & DI	BSCRIPTION	QUALITY	WI GET	G 1	G 1	G 3	G 4	r 6
1	1101970		Arm Body			23.5	1				
2	GY05867	1	Claw BT			0.9	2				
3	GY05871	3	Claw BT			0.7	2				
4	RY30002	2	Key			0.11	2				
5			Constarsunk Haus Serew	5×10			12				
6	RY32043	5	Piston			0.05	4				
7	RY30005		Lock pin			0.09	2				
8	RY30006	2	Pin			0.01	4				
9	4108946		Cover			0.3	2				_
10	RY30008	2	Pla			0.06	4				
11			Circrip	14			4				
12	RY30010	1	Spaser			0.01	4				
13	RY30004	1	Cover			0.07	2				
14		_	Spring Pla	8×30			4				
15			Spring	TR17×45			2				
16			'O' RING	P14			4				
17			Spring	LR8×40			2				
18			Bush	LFB1412			6				
19			Socket Button Hond Serer	8×25			4				
20			Socket Plug	NPT1/16			6				
21			Socket Butten Bead Screw	5×10			10				
22	GY08617	1	Claw ANSi			0.7	2				
23	GY08618	1	CILW ANSI			0.7	2				
24	GY08615	1	Claw DiN			0.7	2				
2.5	CV02616	1	Class DiN			0 7	9				





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E1:2 7 * CITERENT IS DEC. 11 TITLE MANDAI AR **C-C** (S-1:1) MANDAI ARM ASSY MANDAI ARM ASSY HAAS ATC WORI-MACHINERY-CORPORATION 1 M 2 0, 9 7 A







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mi ie	D, W, G M	ю,	PART NAME &	DESCRIPTION	QUALITY	FRIGE	÷,	۰,	۰,	0,	
1			Sol Operated Directional Valve	HD1-3W-BGA-8254-WTA3			3				
2			Sol Operated Directional Value	ED1-39-ALB-425A-97A3			1				
3		T	Compound Valve	HK73H-W-Y2-40K-021B			2				
4			Throttle Valve	HF3H-W-40K-025B			1				
5	3MD1491	L .	Block				1				
6			Throttle Valve	HF3H-P-40K-0258			1				
7			Blto Kits	BD-4-824-82TY2			1				
8						I		_			
9			Socket Head Capacraw	HKS-NA-5×11	-		12				
10			Socket Head Capacrew	5×120			4				
11			Joint	KCT10030B			2				
12			Bushing	SBU04-030J			2				
13			Hose Joint	9034-06			4				
14			Hose Joint	1034-06			4				
15		T									



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2000-04-22 Mori Machinery Corporation NORIAKI YASUHARA

1:Changer swing (MG<->SP 90) Changer assembly (1M2164A-4/4) Part No.231 Hyd, Cylinder

> -1)Cushion adjustment The end of Magazine -> Spindle side ->

Rod side Head side

-2)Speed adjustment Valbe assembly (1M2102A) It is done with the flow control valve under the valve for the changer swing.

2:Changer slide (Right<->Left) Changer assembly (1M2164A-2/4) Part No.61 Hyd, Motor

> -1)Cushion adjustment It is done with the shock absorber of the partial number 95.

-2)Speed adjustment Valbe assembly (1M2102A) It is done with the flow control valve under the valve for the changer slide.

3:Arm rotation (180CW-CCW) Changer assembly (1M2164A-2/4) The hydraulic cylinder of the partial number 57.

-1)Cushion adjustment

CW side -> Head side CCW side -> Rod side

-2)Speed adjustment

Valbe assembly

(1M2102A)

It is done with the flow control valve under the valve for the arm rotation.



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exchange process document

1:It turn at 90 by the changer turn on the magazine side, and the power supply is cut off.

2: It is made the condition that a papeing to the hydraulic motor for the changer slide is loosened and that a changer is pushed by hand and which can be moved.

3:A changer is pushed by hand in the right direction, and stopped in the magazine end front.

4:A cam follower can be removed at the same time by removing the bracket installed under the changer body, too. A bracket removes 3-M10 screw.

5: The cam follower shaft which breaks in the bracket is removed first.

6:A looseness stop does with the M6 set screw in the cam follower shaft from the side.

7:If a shaft comes off, only a new shaft is thrust. Thrust it by using the wrench to the end.

8:A looseness stop is done with the M6 set screw from the side.

Use it if there is a screw lock (bond).

Put a hollow on the cam follower shaft a little in the drill of 4mm, and then do a M6 set screw when there is no bond.

9:A cam follower is inserted into the shaft, and fixed with the external retaining ring.

10:A bracket is assembled under the changer body.

11:If work is completed, a hydraulic papeing is returned to the cause in the next to push a changer body to the right end, and it is completion.



番号:

1

タイトル:

ノート・:

Cling to the changer body.

> モリマシナリ (株) 古井工唱

The adjustment process of the ATC changer cam follower

1:It confirms whether a cam follower is in the center of the groove under the condition on the changer 90 turn magazine side.

2:When a guide hits a cam follower, a stopper bolt at the end of 90 turn magazine is adjusted and adjusted in the center of the guide.

3:A turn spindle side is adjusted at 90 with the process which is the same as the item 1-2, too.

4:90 turn movement is repeated by the manual operation, and a shock at each stroke end is confirmed.

5: It is adjusted with the cushion of the cylinder if a changer unit seems to bound in the turn direction at the stroke end.

6:It is adjusted with doing speed adjustment with the flow control valve of the cylinder hydraulic circuit and keeping a balance when bound can't be absorbed only with the cylinder cushion.

slide :1.0sec(right,left)

90turn :1.4sec(Magazine side, spindle side)

7:By the automatic operation, confirmation

Confirmation is done under the condition which makes one side (magazine side) of the arm have the tool of the maximum weight.



モリマシナリー(株) 吉井工場

Shock absorber adjustment point document

2000/05/02 Mori Machinery Corporation NORIAKI YASUHARA

This shock absorber can't be used as a stopper at the rod stroke end. Set it up by the following point.

- 1. Set it on the position of 15mm from the tip of the rod, and the end face of the stopper nut is to lock a shock absorber with the lock nut under the free condition.
- 2. Set up an absorption energy adjustment knob in the position of 強, and tighten a lock screw on the side of the shock absorber, and lock.
- 3. Turn an absorber itself, and adjust position adjustment at the end of the changer slide, and fix it with the lock nut.

Attention: It can't be adjusted with the stopper nut.



MORI MACHINERY CORPORATION

HS-3/R ATC 38 HYDRAULIC TOOL CHANGER SPARE PARTS

The HS-3/R horizontal milling machine is available with an optional 38 pocket tool changer supplied by the Mori Machine company (OPTION No.: SMTC50-H3, tool changer P/N: 30-0458, MORI 1M01964 (ATC 38)). This document lists the HAAS part numbers for the spare parts available for this tool changer and provides the physical location of these spare parts on the tool changer.

ASSEMBLY NAME	ITEM NO.	PART NAME	HAAS PART NO.
MAGAZINE ASSEMBLY	1	PBOXIMITY SWITCH (TOOL	93-0171
		POCKET NO.1 DETECT, POT	
MAIN DRIVE ASSEMBLY	2	PBOXIMITY SWITCH (INDEX	93-0172
	2	LOCK PIN ARM SLIDE	30 0172
		LEET/BIGHT/CENTER ARM	
		10/001)	
	3	INDEX MOTOR, HYDRAULIC	93-0173
	25		00.0700
	35	VALVE	93-0702
	36	SOLENOID OPERATED	93-0703
		VALVE	
TOOL RELEASE ASSEMBLY	4	SOLENOID OPERATED	93-0174
	5	BEED SWITCH TOOL	93-0175
	5	RELEASE CYLINDER	00 0110
ARM ASSEMBLY	6	ARM ASSEMBLY	93-0176
	7	GRIPPER CLAW "A", ANSI	93-0177
	8	GRIPPER CLAW "B", ANSI	93-0178
	9	LOCK PIN, GRIPPER CLAW	93-0179
	10		03-0100
	10	PIVOT PIN	99-0190
TOOL CHANGER SWING ASSEMBLY	11	SLIDE MOTOR, HYDRAULIC	93-0181
	12	SHOCK ABSORBER	93-0182
	13	STOPPER NUT, SHOCK	93-0183
		ABSORBER	
	14	ROLLER FOLLOWER	93-0184
	15	SHAFT, ROLLER FOLLOWER	93-0185
	16		02.0196
	10	FOLLOWER SHAFT, 14mm	93-0100
	17	REED SWITCH (ARM ROT.	93-0187
		CW/CCW, SWING ARM	
	10	MAG./SPIN.)	00.0100
	18	HYDRAULIC HOSE, MOTOR,	93-0188
	19	HYDBAULIC HOSE ABM IN	93-0189
	10		00 0100
	20	HYDRAULIC HOSE, ARM	93-0190
		OUT	
	21	HYDRAULIC HOSE, ARM	93-0191
	00		02.0100
	22	BOTATE CW	93-0192
	23	HYDRAULIC HOSE, MOTOR	93-0193
		SLIDE LEFT	
	24	HYDRAULIC HOSE, ROTATE	93-0194
		CYL., ROD END, 450mm	
	05		00.0105
	25	CVL CAR END 625mm	93-0195
		CTL., CAP END, 625IIIII	
HYDRAULIC VALVE ASSEMBLY	26	SOLENOID OPERATED	93-0196
	20	VALVE, ARM SWING, IN/OUT.	50 0100
		ROTATE	
	27		93-0197
		SOLENOID VALVE,	
		CHANGER ARM SLIDE	00.0100
	28	SOLENOID, CHANGER ARM	93-0198
	20		93-0155
	23		93-0155
	30	DRIVE MOTOR	93-0150
	32	BETUBN FILTER	93-0158
	33	HYDRAULIC HOSE.	52-0008
		PRESSURE	
	34	HYDRAULIC HOSE, RETURN	52-0000































